

**Geometry**  
**Second Semester 2011/12**  
 Homework 4

1. For what values of  $c$  is the level set  $f^{-1}(c)$  an  $n$ -surface for each  $f$  given below.
  - (a)  $f(x_1, x_2, \dots, x_{n+1}) = x_1^2 + x_2^2 + \dots + x_{n+1}^2$
  - (b)  $f(x_1, x_2, \dots, x_{n+1}) = x_1^2 + x_2^2 + \dots + x_n^2 - x_{n+1}^2$
  - (c)  $f(x_1, x_2, \dots, x_{n+1}) = x_1 x_2 \dots x_{n+1} + 1$
2. Show that the cylinder  $\{(x_1, x_2, x_3) \mid x_1^2 + x_2^2 = 1\} \subset \mathbf{R}^3$  can be represented as the level set of each of the following functions.
  - (a)  $f(x_1, x_2, x_3) = x_1^2 + x_2^2$
  - (b)  $f(x_1, x_2, x_3) = -x_1^2 - x_2^2$
  - (c)  $f(x_1, x_2, x_3) = 2x_1^2 + 2x_2^2 + \sin(x_1^2 + x_2^2)$
3. Show that if an  $n$ -surface  $S$  is represented as both  $f^{-1}(c)$  and  $g^{-1}(d)$ , for smooth functions  $f$  and  $g$ , and numbers  $c, d \in \mathbf{R}$ , where  $\nabla f(p) \neq \mathbf{0}$  and  $\nabla g(p) \neq \mathbf{0}$  for all  $p \in S$ , then, for each  $p \in S$ ,  $\nabla f(p) = \lambda \nabla g(p)$  for some real number  $\lambda \neq 0$ .
4. Sketch the cylinders  $f^{-1}(0)$  for the following functions  $f$ .
  - (a)  $f(x_1, x_2) = x_1$
  - (b)  $f(x_1, x_2, x_3) = x_1 - x_2^2$
  - (c)  $f(x_1, x_2, x_3) = x_1^2/4 + x_2^2/9 - 1$
5. Verify that a surface of revolution (see Example 4.6 in your notes) is a 2-surface.
6. Sketch the surface of revolution obtained by rotating  $C$  about the  $x_1$ -axis, where  $C$  is each of the curves defined below.
  - (a)  $\{(x_1, x_2) \mid x_2 = 1\}$  (cylinder)
  - (b)  $\{(x_1, x_2) \mid -x_1^2 + x_2^2 = 1, x_2 > 0\}$  (1-sheeted hyperboloid)
  - (c)  $\{(x_1, x_2) \mid x_1^2 + (x_2 - 2)^2 = 1\}$  (torus)
7. Show that the set  $S$  of all unit vectors at all points in  $\mathbf{R}^2$  forms a 3-surface in  $\mathbf{R}^4$ . Hint:  $S = \{(x_1, x_2, x_3, x_4) \mid x_3^2 + x_4^2 = 1\}$ .
8. Let  $S = f^{-1}(c)$  be a 2-surface in  $\mathbf{R}^3$  which lies in the half-space  $\{(x_1, x_2, x_3) \mid x_3 > 0\}$ . Find a function  $g: U \rightarrow \mathbf{R}$  (where  $U$  an open set in  $\mathbf{R}^4$ ) such that  $g^{-1}(c)$  is the 3-surface obtained by rotating the 2-surface  $S$  about the  $(x_1, x_2)$ -plane.
9. Let  $a, b, c \in \mathbf{R}$  be such that  $ac - b^2 > 0$ . Show that the maximum and minimum values of the function  $g(x_1, x_2) = x_1^2 + x_2^2$  on the ellipse  $\{(x_1, x_2) \mid ax_1^2 + 2bx_1x_2 + cx_2^2 = 1\}$  are of the form  $1/\lambda_1$  and  $1/\lambda_2$ , where  $\lambda_1$  and  $\lambda_2$  are the eigenvalues of the matrix  $\begin{pmatrix} a & b \\ b & c \end{pmatrix}$ .
10. Let  $S$  be an  $n$ -surface in  $\mathbf{R}^{n+1}$  and let  $p_0 \in \mathbf{R}^{n+1} \setminus S$ . Show that the shortest line segment from  $p_0$  to  $S$  (if one exists) is perpendicular to  $S$ . That is, show that if  $p \in S$  is such that  $\|p_0 - p\|^2 \leq \|p_0 - q\|^2$  for all  $q \in S$ , then  $(p, p_0 - p) \perp S_p$ . [Hint: Use the Lagrange Multiplier Theorem.] Show that the same conclusion holds for the longest line segment from  $p_0$  to  $S$  (again, if one exists).
11. The set  $\mathbf{R}^4$  may be viewed as the set of all  $2 \times 2$  matrices with real entries by identifying the quadruple  $(x_1, x_2, x_3, x_4)$  with the matrix

$$\begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix}.$$

The subset consisting of those matrices with determinant equal to one forms a group under matrix multiplication, this group is called the special linear group  $SL(2)$ . Show that  $SL(2)$  is a 3-surface in  $\mathbf{R}^4$ .

12. The trace of a matrix

$$A = \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix}$$

is defined to be  $\text{tr}(A) := x_1 + x_4$ . Show that the tangent space  $SL(2)_p$  to  $SL(2)$  (see Question 11) at  $p = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$  can be identified with the set of all  $2 \times 2$  matrices of trace zero by showing that

$$SL(2)_p = \left\{ \left( p, \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix} \right) \mid x_1 + x_4 = 0 \right\}.$$

[Hint: First show that if

$$\alpha(t) = \begin{pmatrix} x_1(t) & x_2(t) \\ x_3(t) & x_4(t) \end{pmatrix}$$

is a parametrised curve in  $SL(2)$  with  $\alpha(0) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$  then  $x'_1(0) + x'_4(0) = 0$ . Use a dimensional argument to prove the opposite inclusion.]